

We were discussing  
multilinear maps.

Example 1: (dot product)

$$\mathbb{R}^n \times \mathbb{R}^n, v, w \in \mathbb{R}^n$$

Define a bilinear map on  $\mathbb{R}^n$  by

$$(\cdot, \cdot) : \mathbb{R}^n \rightarrow \mathbb{R}$$

$$(v, w) = \sum_{i=1}^n v_i w_i = v \cdot w$$

if  $v = (v_1, \dots, v_n)$ ,  $w = (w_1, \dots, w_n)$

The difference between this and example 1 last time is that  $v$  and  $w$  are both allowed to vary here.

Check bilinearity!

let  $v = (v_1, \dots, v_n)$ .

$$\begin{aligned}(v+w, w) &= \sum_{i=1}^n (v_i + w_i) w_i \\ &= \sum_{i=1}^n v_i w_i + \sum_{i=1}^n w_i w_i \\ &= (v, w) + (w, w)\end{aligned}$$

Linearity in the second coordinate is a similar calculation. Now if  $c \in \mathbb{R}$ ,

$$(c\nu, \omega) = \sum_{i=1}^n (c\nu_i) \omega_i$$

$$= c \sum_{i=1}^n \nu_i \omega_i$$

$$= c(\nu, \omega),$$

second coordinate is similar.

Observe:  $(\cdot, \cdot)$  is not

linear as a map from

$$\mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$$

For example, if  $(e_i)_{i=1}^n$  is the standard basis of  $\mathbb{R}^n$ ,

$$(e_i, 0) + (0, e_i) = 0$$

$$\text{but } (e_i, e_i) = 1.$$

Example 2:  (determinants)

$$\text{Let } A = (a_{i,j})_{i,j=1}^n$$

be an  $n \times n$  matrix.

Let  $a_i$ ,  $1 \leq i \leq n$ , be the  
vector

$$a_i = (a_{1,i}, a_{2,i}, \dots, a_{n,i})$$

(columns of  $A$ )

Define  $\det(A)$  as a multilinear map from

$$\underbrace{\mathbb{R}^n \times \mathbb{R}^n \times \dots \times \mathbb{R}^n}_{n \text{ times}}$$

$$\det(a_1, a_2, \dots, a_n)$$

$$= \sum_{\sigma \in S_n} \text{sign}(\sigma) a_{1, \sigma(1)} a_{2, \sigma(2)} \dots a_{n, \sigma(n)}$$

$$\in \mathbb{R}$$

Where

$S_n =$  all bijections from  $\{1, 2, \dots, n\}$  to itself.

Each such element can be expressed as a product of transpositions. A

transposition is a map from  $\{1, 2, \dots, n\}$  to itself that

fixes all but two elements and interchanges the remaining 2.



Example:  $n=4$

$$\{1, 2, 3, 4\} \xrightarrow{\sigma} \{1, 2, 3, 4\}$$

$$\sigma(1) = 1$$

$$\sigma(2) = 4$$

$$\sigma(3) = 3$$

$$\sigma(4) = 2$$

is a transposition.

Although any  $\sigma \in S_n$   
is a product of transpositions,  
the representation is not  
unique (unless  $n=1$ ).

However, the **parity** (even  
or odd number of  
transpositions) **is** unique.

Define

$$\text{Sign}(\sigma) = \begin{cases} 1, & \sigma \text{ is a product of} \\ & \text{an even number} \\ & \text{of transpositions} \\ -1, & \sigma \text{ a product of an} \\ & \text{odd number} \end{cases}$$

Observe, then, that  
if  $\sigma$  is a transposition,  
 $\text{sign}(\sigma) = -1$ .

Moreover, if  $\sigma, \tau \in S_n$ ,

$$\text{Sign}(\sigma \circ \tau) = \text{sign}(\sigma) \text{sign}(\tau)$$

Let's show det is multilinear. Look at the first coordinate.

$$\det(a_1 + b_1, a_2, a_3, \dots, a_n)$$

$$= \sum_{\sigma \in S_n} \text{sign}(\sigma) (a_{1, \sigma(1)} + b_{1, \sigma(1)}) \cdot a_{2, \sigma(2)} \cdots a_{n, \sigma(n)}$$

$$= \sum_{\sigma \in S_n} \text{sign}(\sigma) (a_{1, \sigma(1)} \cdot a_{2, \sigma(2)} \cdots a_{n, \sigma(n)}) + \sum_{\sigma \in S_n} \text{sign}(\sigma) (b_{1, \sigma(1)} \cdot a_{2, \sigma(2)} \cdots a_{n, \sigma(n)})$$

$$= \det(a_1, a_2, \dots, a_n) \\ + \det(b_1, b_2, \dots, b_n)$$

A similar calculation holds

for the other entries, scalar  
multiplication follows from  
the definition :

Let  $c \in \mathbb{R}$ .

$$\det(ca_1, a_2, \dots, a_n)$$

$$= \sum_{\sigma \in S_n} \text{sign}(\sigma) c a_{1, \sigma(1)} a_{2, \sigma(2)} \cdots a_{n, \sigma(n)}$$

$$= c \sum_{\sigma \in S_n} \text{sign}(\sigma) a_{1, \sigma(1)} \cdots a_{n, \sigma(n)}$$

$$= c \det(a_1, a_2, \dots, a_n).$$

Other coordinates similar.

Observe: If  $\gamma \in S_n$ ,

then

$$\det(a_{\gamma(1)}, a_{\gamma(2)}, \dots, a_{\gamma(n)}) \\ = \text{sign}(\gamma) \det(a_1, a_2, \dots, a_n)$$

In particular, if  $\gamma$  is a  
transposition, then

$$\det(a_{\gamma(1)}, a_{\gamma(2)}, \dots, a_{\gamma(n)}) \\ = - \det(a_1, a_2, \dots, a_n)$$

$$\det(a_{jk(1)}, a_{jk(2)}, \dots, a_{jk(n)})$$

$$= \sum_{\sigma \in S_n} \text{sign}(\sigma) a_{1, \sigma(1)} a_{2, \sigma(2)} \dots a_{n, \sigma(n)}$$

$$= \sum_{\sigma \in S_n} \text{sign}(\sigma) \text{sign}(\gamma) \text{sign}(\delta) a_{1, \sigma(\delta(1))} \dots a_{n, \sigma(\delta(n))}$$

$$= \text{sign}(\delta) \sum_{\sigma \in S_n} \text{sign}(\sigma \circ \delta) a_{1, \sigma(\delta(1))} \dots a_{n, \sigma(\delta(n))}$$

$$= \text{sign}(\delta) \sum_{\sigma \circ \delta \in S_n} \text{sign}(\sigma \circ \delta) a_{1, \sigma(\delta(1))} \dots a_{n, \sigma(\delta(n))}$$

(if we set  $\tau = \sigma \circ \delta$ )

$$= \text{sign}(\delta) \sum_{\tau \in S_n} \text{sign}(\tau) a_{1, \tau(1)} \dots a_{n, \tau(n)}$$



$$= \text{sign}(\tau) \det(a_1, \dots, a_n)$$

Such a multilinear  
form  $T$ , where

$$T(v_{\sigma(1)}, \dots, v_{\sigma(n)}) \\ = \text{sign}(\sigma) T(v_1, \dots, v_n)$$

is called **alternating**.